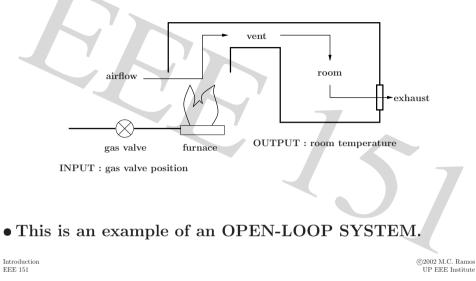
- Open-loop vs. closed-loop.
- Advantages and disadvantages of a closed-loop system.
- Control system design overview.

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Why Feedback?

- How can we control the system?
 - for different actions (at the input), determine the effects (at the output) on the system.
 - -we have a input to output map of the system.
 - -we want the output behave a specific way.
 - invert the input to output relationship, i.e., determine for a given output what the necessary input is.
- For the room heating example, we want the output temperatures for different valve settings.
 - We then set the valve to the corresponding temperature we want.

• Example. Room heating



Why Feedback?

- This control solution is termed inversion.
- Problem :
 - what if the number of people in the room increases?- what if somebody opens a window?
- Result : temperature change.
- Even though our valve is at the "right" setting, the room temperature is not at the desired level.
- \Rightarrow The model changed.

- In general, inversion does not usually lead to a satisfactory solution unless
 - -we have a very good representation of the plant,
 - the plant model and its inverse are stable, and
 - disturbances and initial conditions are negligible.
- We need to find an alternative solution to inversion.
- Solution: monitor the room temperature.

Change the gas valve position such that

- $-LOW \text{ TEMP} \Rightarrow \text{more gas.}$
- -HIGH TEMP \Rightarrow less gas.

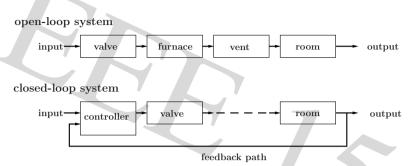
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Open-loop vs. Closed-loop

- Advantages of a closed-loop system.
 - output is less sensitive to DISTURBANCES (e.g. more people in room, window opens).
 - output is less sensitive to PLANT CHANGES (e.g. aging furnace, improved insulation).
 - -output is more accurate with respect to desired value.

• Disadvantages of a closed-loop system.

- controller and sensor cost money.
- system may become unstable if improperly designed (e.g. steam governor, Mars rover).

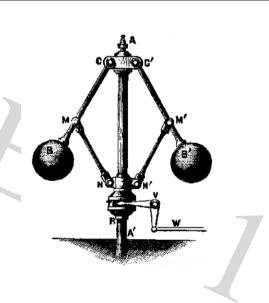


• We will see later that a properly designed closed-loop system works similar to inversion but without the problems.

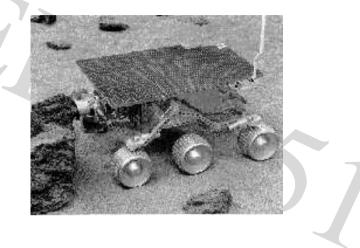
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Open-loop vs. Closed-loop

• Steam governor. Becomes unstable if mechanisms are too smooth.



©2002 M.C. Ramos UP EEE Institute Introduction EEE 151 • Mars rover - too much delay leads to "instability."

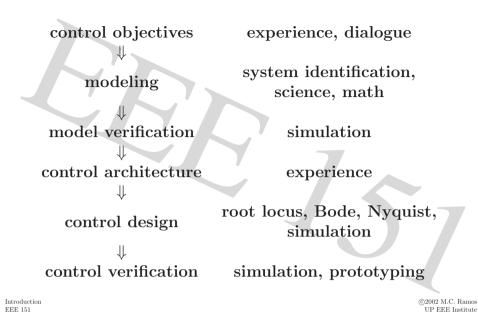


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Control System : Objectives

- What do you want the control to achieve? – enhance quality.
 - -energy reduction.
 - -increase yield.
- What variables need to be controlled to achieve the objectives?
- What level of performance is necessary?
 - -accuracy (error < 5%).
 - -speed (system needs to settle in 1 minute).

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Control System : Modeling

- Gaining understanding of how the process operates. The model is usually expressed in mathematical form.
- Finding the right model is key to proper design.
 - the model must be simple enough so as not to complicate the controller design.
 - the model must also be accurate enough to provide a good undestanding how the process works.
- Example. Diode model.

You need to determine the appropriate model for the circuit you are designing.

- It is often necessary to go back one or more steps and repeat the process.
- What controller?
 - -classical, fuzzy, neural.
 - does it take into account modeling errors?
 - -how does it react to disturbances and noise?
 - cost and complexity.

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- What is a closed-loop system? How is it different from an open-loop system?
- Advantages and disadvantages of a closed-loop system.
- Control system design.

• Homework. Text P{ 1.1, 1.2, 1.6, 1.8 }, DP{ 1.1, 1.2 }

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