

Outline of Today's Lecture

- What are **Hurwitz determinants**, and how do they help us to see whether a system is stable or not.
- What is the **Routh-Hurwitz stability criterion**?
What is an R-H table?
- Why do you want to use **Routh-Hurwitz stability test**?
Why not just find the poles and decide from there?
- Some examples and **exercises** on using R-H stability test.

Routh-Hurwitz Stability Test

- **Theorem.**
All roots lie in the **left half plane** if and only if **Hurwitz determinants** are positive.

$$D(s) = a_0 s^n + a_1 s^{n-1} + \dots + a_{n-1} s + a_n = 0$$

$$D_1 = a_1$$

$$D_2 = \begin{vmatrix} a_1 & a_3 \\ a_0 & a_2 \end{vmatrix}$$

$$D_3 = \begin{vmatrix} a_1 & a_3 & a_5 \\ a_0 & a_2 & a_4 \\ 0 & a_1 & a_3 \end{vmatrix}$$

$$\vdots$$
$$D_n = \dots$$

Routh-Hurwitz Stability Test

- Why study the **Routh-Hurwitz test**?
The **Routh-Hurwitz test** is a method for whether or not a system is stable based upon the coefficients in the system's characteristic equation.
- **Quick check** for stability given the **polynomial**.
- Based on the concept of **Hurwitz determinants**.

Routh-Hurwitz Stability Test

- If we already can deduce **stability** from **Hurwitz determinants**, what did **Routh** do?
Routh simplified the **Hurwitz determinants** into a **tabular method**.
- Useful for determining **stability limits**, i.e., what gain **k** makes a control **system** stable.
- Particularly useful for **higher-order systems** because it does not require the **polynomial** in the **transfer function** to be factored.

The Method

- Write the characteristic equation in the following form.

$$a_0s^n + a_1s^{n-1} + \dots + a_{n-1}s + a_n = 0$$

- Important note before using R-H test.

If any of the coefficients are zero or negative and at least one of the coefficients is positive, there is a \dots there are roots that are imaginary or that have positive real parts.

Then, the system is \dots stable or unstable.

The Method

- The Routh- \dots stability criterion states that the number of roots with positive real parts is equal to the number of sign changes of the coefficients in the first column of the table.

- Note that the exact values are not required for the coefficients; only the sign matters.

- Used to be harder to find \dots than apply R-H test.

The Method

- Routh-Hurwitz (R-H) \dots .

$$\begin{array}{rcccc}
 s^n & : & a_0 & & a_2 & & a_4 & \dots \\
 s^{n-1} & : & a_1 & & a_3 & & a_5 & \dots \\
 s^{n-2} & : & b_1 = \frac{a_1a_2 - a_0a_3}{a_1} & & b_2 = \frac{a_1a_4 - a_0a_5}{a_1} & & \dots & \dots \\
 s^{n-3} & : & c_1 = \frac{b_1a_3 - a_1b_2}{b_1} & & \dots & & \dots & \dots \\
 & & \vdots & & \vdots & & \vdots & \dots \\
 & & \vdots & & \vdots & & \vdots & \dots \\
 s^1 & : & d_1 = \dots & & d_2 = \dots & & & \dots \\
 s^0 & : & e_1 = \dots & & & & & \dots
 \end{array}$$

The Method

- R-H test may be used to determine the regions of stability, i.e., what range of feedback parameters will \dots the system stable.

- Root locus provides the same information in a graphical manner.

- Advances in computing have reduced the usage of R-H test.

Examples

- Simple example.

Given a system with characteristic equation

$$a_0s^2 + a_1s + a_2 = 0$$

Determine which values of the coefficients will make the system stable and which will make the system .

- Arranged in R-H table form.

$$\begin{array}{l}
 s^2 : \quad a_0 \quad a_2 \\
 s^1 : \quad a_1 \\
 s^0 : \quad \frac{a_1a_2 - a_0 \cdot 0}{a_1}
 \end{array}$$

Examples

- Another example.

Consider the system with characteristic equation

$$s^3 + s^2 + 2s + 24 = 0$$

- R-H table format.

$$\begin{array}{l}
 s^3 : \quad 1 \quad 2 \\
 s^2 : \quad 1 \quad 24 \\
 s^1 : \quad \frac{1 \cdot 2 - 1 \cdot 24}{1} = -22 \\
 s^0 : \quad \frac{-22 \cdot 24 - 1 \cdot 0}{-22} = 24
 \end{array}$$

Examples

- Simplified.

$$\begin{array}{l}
 s^2 : a_0 \quad a_2 \\
 s^1 : a_1 \\
 s^0 : a_2
 \end{array}$$

- According to R-H, for , there should be no sign change in the first column.

- Therefore, for , $a_i > 0$ for all $i = 0, 1, 2$.

Examples

- Since there is at least one sign in the first row of the R-H table, the system is unstable.

- Check with MATLAB.

```
>> roots([1 1 2 24])
```

ans =

```
-3.0000
 1.0000 + 2.6458i
 1.0000 - 2.6458i
```

⇒ It has two roots in the right half-plane.

⇒ The system is unstable.

Examples

- Illustrative example.

What if a zero appears in the first column?

Consider the system with characteristic equation

$$s^5 + 2s^4 + 2s^3 + 4s^2 + 11s + 10 = 0$$

- Constructing the R-H table,

$$\begin{array}{r}
 s^5 : \quad 1 \qquad \qquad \qquad 2 \qquad \qquad 11 \\
 s^4 : \quad 2 \qquad \qquad \qquad 4 \qquad \qquad 10 \\
 s^3 : \quad \boxed{\frac{2 \cdot 2 - 1 \cdot 4}{2} = 0} \quad \boxed{\frac{2 \cdot 11 - 1 \cdot 10}{2} = 6}
 \end{array}$$

Examples

- A zero appears in the first column.

We will have a problem constructing the succeeding rows of R-H table (division by zero).

- Recall that we are interested only in the sign of the coefficients.

- Workaround is to replace the 0 with a small, positive number, ϵ .

Examples

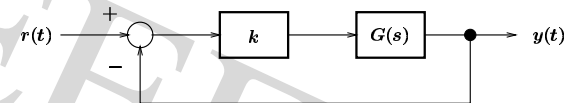
- Continue constructing the R-H table.

$$\begin{array}{r}
 s^5 : \quad 1 \qquad \qquad \qquad 2 \qquad \qquad 11 \\
 s^4 : \quad 2 \qquad \qquad \qquad 4 \qquad \qquad 10 \\
 s^3 : \quad \epsilon \qquad \qquad \qquad 6 \\
 s^2 : \quad \boxed{\frac{\epsilon \cdot 4 - 2 \cdot 6}{\epsilon} = \frac{-12}{\epsilon}} \quad \boxed{\frac{\epsilon \cdot 10 - 2 \cdot 0}{\epsilon} = 10} \\
 s^1 : \quad \boxed{\frac{\frac{-12}{\epsilon} \cdot 6 - \epsilon \cdot 10}{\frac{-12}{\epsilon}} = 6} \\
 s^0 : \quad \boxed{\frac{6 \cdot 10 - \frac{-12}{\epsilon} \cdot 0}{6} = 10}
 \end{array}$$

sign changes in the first column \Rightarrow unstable.

Examples

- Example 1. Consider



where k is a positive constant and

$$G(s) = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}, \quad \zeta > 0, \omega_n > 0$$

- What values of k can destabilize the system?

Examples

- d-ct TF and characteristic equation.

$$\frac{Y(s)}{R(s)} = \frac{kG(s)}{1 + kG(s)}$$

$$s^2 + 2\zeta\omega_n s + (k + 1)\omega_n^2 = 0$$

- R-H table.

$$\begin{array}{l} s^2 : \quad 1 \quad (k + 1)\omega_n^2 \\ s^1 : \quad 2\zeta\omega_n \\ s^0 : (k + 1)\omega_n^2 \end{array}$$

⇒ System is stable for any $k > 0$.

Examples

- Example 2. Consider with $G(s)$

$$G(s) = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2} \cdot \frac{a}{s + a}, \quad k, \zeta, \omega_n, a > 0$$

- Characteristic equation.

$$(s^2 + 2\zeta\omega_n s + \omega_n^2)(s + a) + k\omega_n^2 a = 0$$

Collecting terms.

$$s^3 + (2\zeta\omega_n + a)s^2 + (\omega_n^2 + 2\zeta\omega_n a)s + (k + 1)\omega_n^2 a = 0$$

Examples

- R-H table.

$$\begin{array}{l} s^3 : \quad 1 \quad \omega_n^2 + 2\zeta\omega_n a \\ s^2 : \quad 2\zeta\omega_n + a \quad (k + 1)\omega_n^2 a \\ s^1 : \quad b_1 \\ s^0 : (k + 1)\omega_n^2 a \end{array}$$

where

$$b_1 = \omega_n^2 + 2\zeta\omega_n - \frac{(k + 1)\omega_n^2 a}{2\zeta\omega_n + a}$$

- Therefore, the system is stable for $k > 0$ such that $b_1 > 0$.

Summary and Remarks

- Routh-Hurwitz stability test based on Hurwitz determinants.

Routh simplified the into a tabular method.

- R-H test is useful for quick answers if the transfer function or characteristic equation is exactly known.

- Root locus provides a better method for visualizing the behavior of the roots of the .