Today's EEE 101 Lecture

- What is control systems theory?
- Motivation for control.
- Examples of control systems.
- Basic feedback system.
- Why feedback?

Introduction

©2002 M.C. Ramos UP EEE Department

Objectives of EEE 101

• Identify a system and

- model it.
- Design a controller to meet some given
- Time domain and domain techniques.
- Verify your design.

What is EEE 101?

- Classical concepts of continuous-time feedback system.
 - modeling,
 - na and and
 - -compensation techniques.
- Stability of feedback systems.
 - -root locus,
 - -Bode and Nyquist plots.
- Introduction to computer-aided

tools.

tion I ©2002 M.C. Ramos UP EEE Department

Practical Use of EEE 101?

- Design systems and know how they work.
- Understand other control systems and be able to say why they work (or do not work).
- More importantly,
 - -read and literature.
 - -basic foundation for other control courses.
 - no blank faces when somebody mentions poles and zeros, and Nyquist plots.

k, and

Motivation for Control

- Feedback control began with the human desire to harness the materials and forces of nature to their advantage.
- Early examples include water based regulating systems and mechanisms for keeping windmills point into the wind.
- Sophisticated control is crucial for the successful operation of many modern industrial plants.

Introduction ©2012 M.C. Ramos
EEE 101 UP EEE Department

Examples of Control Systems

• Control of an aircraft.



- engine affects aircraft speed.
- -rudder controls aircraft yaw.
- -elevator controls the pitch.
- aileron controls the of the aircraft.

Motivation for Control

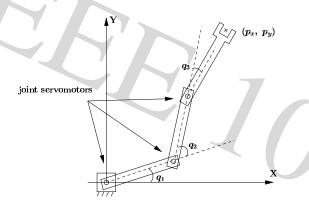
- Control has a major impact on society.
 For example, the fly ball governor had a major impact on the industrial revolution.
- Improved control is an enabling technology.
 - -enhanced product quality.
 - -less waste.
 - -leads to environment friendliness.
 - -greater throughput for a given installed capacity.
 - -greater yield.
 - -deferring costly plant upgrades.
 - -higher safety margins.

Introduction ©2002 M.C. Ramos
EEE 101 UP EEE Department

Examples of Control Systems

• Robotic manipulator.

- servomotors control the angles.



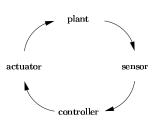
Examples of Control Systems

- Biological system.
 - flow controls bacteria growth.
 - -input is nutrient material.
 - output is the bacteria
- Population system.
 - population on different factors.
 - -inputs may be food and climate conditions.
 - output is population.

Basic Elements of a Control System

• Plant.

This is the process you want to control, i.e., drive to the desired state.



• You need to be familiar with the physics of the process in order to control it.

Requires knowledge of basic energy balance, mass balance and material flows in the system.

Basic Elements of a Control System

- Consider the problem of controlling the light intensity of a bulb.
- We have two light bulbs.
 - we set the intensity of one bulb (bulb A).
 - then we try to match the intensity of the other bulb (bulb B) to the intensity of bulb A.
- Simple control system.

What are the parts of the system?

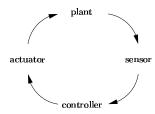
 Introduction
 ©2002 M.C. Ramos

 EEE 101
 UP EEE Department

Basic Elements of a Control System

• Sensor.

Eye of the control. Enables the control to see what is going on. Reports on the state of the process.



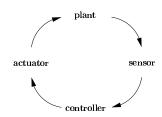
Actuator.

Moves the process from current state to the desired state. If the sensor is the eye, then the actuator is the muscle.

Basic Elements of a Control System

• Controller.

Takes the sensor information and decides how to actuate the plant to achieve the desired state.



• In this course, we will concentrate on the design of a controller for a system.

The sensor and actuator will usually be abstracted.

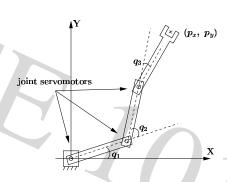
In reality, the sensor and actuator are as much a part of the design as the controller is.

Introduction ©2002 M.C. Ramos EEE 101 UP EEE Department

Basic Elements of a Control System

• Robotic manipulator.

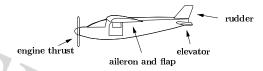
- Servomotors are the actuators.
- Sensors are shaft encoders.



 \bullet No need for x, y end-effector position sensor. Why?

Basic Elements of a Control System

• Control of an aircraft.



- Actuators are
- -engine
- -rudder, elevator and aileron.
- Sensors could be
- aircraft speed sensor.
- -pitch, roll, yaw angle sensors.

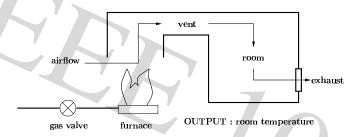
Introduction ©2002 M.C. Ramos EEE 101 UP EEE Department

Basic Elements of a Control System

- Biological system.
 - the acuator is the material.
 - the sensor could be an image processing system coupled to a microscope.
- Population system.
 - the actuators are food and climate conditions.
 - the sensor could be random population sampling.

Why Feedback?

• Example. Room heating.



INPUT: gas valve position

• This is an example of an

SYSTEM.

introduction ©2022 M.C. Ramos EEE 101 UP EEE Department

Summary

- Why EEE 101?
- Examples of control systems.
- Parts of a control system. Why feedback?
- Next time.
 - -open-loop vs.
 - advantages and disadvantages of a closed-loop system.
 - -control design overview.

Why Feedback?

- Problem:
 - what if the number of people in the room increases?
 - what if opens a window?
- Result: temperature change.
- Solution: monitor the room temperature. Change the gas valve position such that
 - TEMP \Rightarrow more gas.
 - $-HIGH \Rightarrow less gas.$