

EE 233 Experiment 3

- Digital controller implementation.
 - use PIC16F88 as the controller.
 - use the internal 10-bit A/D converter.
 - use 10 digital output bits and R-2R ladder to do D/A conversion.

- Difference equations similar to experiments 1 and 2 will be used. Different coefficients may be specified.

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- Project details.

- $e(k)$ is the input voltage.
- $y(k)$ is the output voltage.
- assume input and output voltage range is 0 to 5 V.
- the voltages are quantized into unsigned 10-bit values.

$$0V \leftrightarrow 0x0000$$

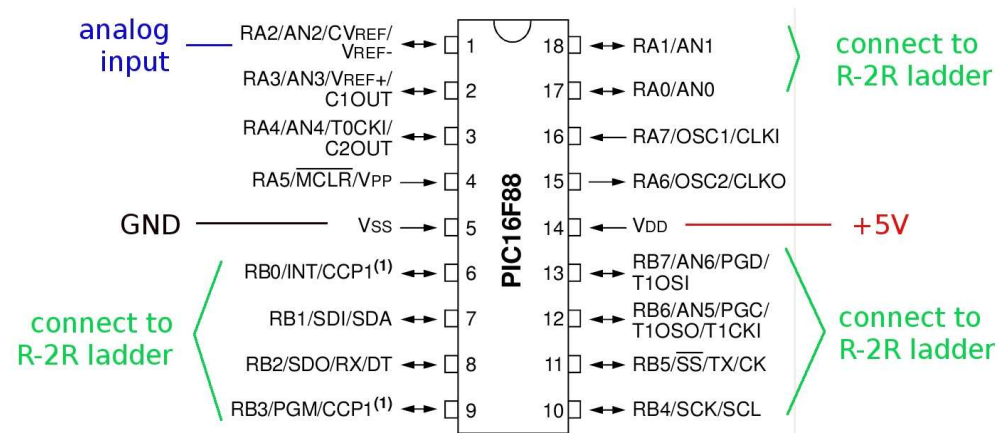
$$5V \leftrightarrow 0x03FF$$

- PIC RA2/AN2 must be used as analog input.
- PIC PA[1:0] and PB[7:0] are to be used with an R-2R ladder for analog output functionality.
- sampling rate is 1 kHz.

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- Build the PIC16F88 setup and program the PIC16F88 to implement the sequential solution to a difference equation.

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PIC Setup



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- Build an appropriate R-2R ladder for D/A conversion.
- PIC16F88s may be borrowed.
- You will need
 - a breadboard to assemble your circuit.
 - resistors for your R-2R ladder.
 - battery to power your circuit.

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- General program flow.
 - initialize the PIC. see sample code.
 - A/D operation. sample analog input. see sample code.
 - implement filter operation : multiply and add operations.
 - D/A operation. use digital outputs. see sample code.
 - repeat : loopback to A/D operation.

- Write the program in assembly. Compile (assemble) with MPASM or gpasm. A PIC programmer will be made available to the class.

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- No internal floating-point number representation and no internal floating-point operations.
 - PIC16F88 only has 8-bit operations.
 - implement 16-bit or 32-bit operations to get reasonable accuracy for your computations.

- Sample code has
 - initialization for 4 MHz internal clock, RA2/AN2 analog input, and PA[1:0] and PB[0:7] digital outputs.
 - routines for A/D and D/A operation.

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- **Deadline is on 24 September 2009. Your work will be tested in the lab.**