- Digital controller implementation.
 - -similar to digital filters.
 - $-\operatorname{control} G(z) \Rightarrow \text{difference equation.}$
 - -boils down to implementing a sequential solution to a difference equation.
- Fixed-point or floating-point?
 - for most control applications, fixed-point is sufficient.
 - -difference equation solution basically multiply and add operations.
 - need to implement floating-point operations on fixed-point processors.

• A/D operation converts voltage to n-bit value (integer). D/A operation converts n-bit value (integer) to voltage.

- Project details.
 - -e(k) is the input voltage.
 - -y(k) is the output voltage.
 - -assume input and output voltage range is -1.65 V to +1.65 V.
 - the voltages are quantized into unsigned 10-bit values.

- Create a C program that will implement the sequential solution to the difference equation.
 - -write the progam assuming no internal floating-point number representation and no internal floating-point operations.
 - -only unsigned int variables are allowed.
 - -only exception are input e(k) and output y(k) variables.

- General program flow.
 - -declarations. choose sampling interval and represent controller coefficients as unsigned int.
 - -initialize : set initial conditions.
 - -A/D operation : convert floating-point input to unsigned int filter input.
 - -filter operation : multiply and add operations.
 - -D/A operation : convert unsigned int filter result to floating-point output.
 - -repeat: loopback to A/D operation.

• Write the program in C (ANSI C). Put in appropriate comments.

• Run the program with zero initial conditions and using the following inputs.

-unit step.

$$-\sin(\omega t)$$
 with $f = 100 Hz$

• Store / plot the input and output samples.

• Verify. Compare the outputs of the C programs for this experiment and experiment 1.