- What is EE 231?
- Motivation for control.
- Examples of control systems.
- Basic control system.

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## Motivation for Control

- Sophisticated control is crucial for the successful operation of many modern industrial plants.
- Improved control is an enabling technology.
  - -enhanced product quality.
  - -less waste.
  - leads to environment friendliness.
  - -greater throughput for a given installed capacity.
  - -greater yield.
  - -deferring costly plant upgrades.
  - -higher safety margins.

- -modeling, transfer functions, block diagrams and SFG.
- -root locus, Bode plots, Nyquist plots.
- -stability.
- Design of controllers.
  - -compensation techniques, PID, phase-lead
  - -sensitivity, disturbance rejection.

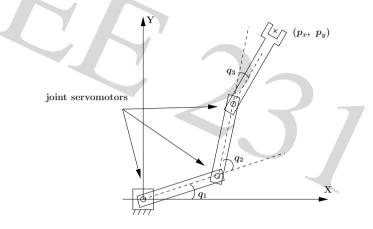
• Multivarible control, robust control, adaptive control.

#### **Examples of Control Systems**

• Control of an aircraft.

engine thrust affects aircraft speed.
rudder controls aircraft yaw.
elevator controls the pitch.
aileron controls the roll of the aircraft.

- Robotic manipulator.
- servomotors control the joint angles.

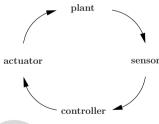


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Basic Elements of a Control System

#### • Plant.

This is the process you want to control, i.e., drive to the desired state.



• You need to be familiar with the physics of the process in order to control it.

Requires knowledge of basic energy balance, mass balance and material flows in the system.

- Biological system.
  - -nutrient flow controls bacteria growth.
  - -input is nutrient material.
  - -output is the bacteria concentration.

• Population system.

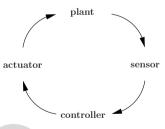
- -population depends on different factors.
- -inputs may be food supply and climate conditions.
- -output is population.

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## Basic Elements of a Control System

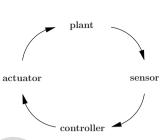
• Sensor.

Eye of the control. Enables the control to see what is going on. Reports on the state of the process.



#### • Actuator.

Moves the process from current state to the desired state. If the sensor is the eye, then the actuator is the muscle. • Controller.



and decides how to actuate the plant to achieve the desired state.

Takes the sensor information

- In this course, we will start with the mathematical representation of the plant.
  - We will then proceed to learn tools for analysis.
  - Look at different control schemes to achieve control objectives.

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## Basic Elements of a Control System

- Robotic manipulator.
- Servomotors are the actuators. • Sensors are shaft encoders.  $q_3$   $q_3$   $q_4$   $q_3$   $q_4$   $q_2$   $q_4$   $q_5$   $q_4$   $q_5$   $q_5$   $q_6$   $q_6$  $q_6$
- No need for x, y end-effector position sensor. Why?

• Control of an aircraft.



- Actuators are
  - -engine thrust.
  - -rudder, elevator and aileron.
- Sensors could be
  - $-\operatorname{aircraft}$  speed sensor.
  - $-\operatorname{pitch}$ , roll, yaw angle sensors.

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# Basic Elements of a Control System

- Biological system.
  - the actuator is the nutrient material.
  - the sensor could be an image processing system coupled to a microscope.
- Population system.
  - the actuators are food supply and climate conditions.
- the sensor could be random population sampling.

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- Why EE 231?
- Examples of control systems.
- Parts of a control system.
- Next time.
  - mathematic modeling.
  - -block diagrams.
  - -signal flow graphs.

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